## Computing Science (CMPUT) 455 Search, Knowledge, and Simulations

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- AlphaGo Zero
- USRI Evaluations open Dec 1-Thu Dec 9
- Coursework:
  - Work on Assignment 4 (due Tue, Dec 14)
  - Reading: AlphaGo Zero paper
  - Quiz 12: Reinforcement Learning and AlphaGo

## USRI (Universal Student Ratings of Instruction)

- You should have received an email
- If not, use this link: https://p20.courseval.net/ etw/ets/et.asp?nxappid=UA2&nxmid=start
- Important part of evaluating this course
- Part of instructor and TA's annual evaluation
- Please fill it out!

- October 2017 article in Nature
- Mastering the game of Go without human knowledge
- New simplified architecture
- Learns entirely from self-play
- No human knowledge beyond the basics such as rules of game
- Stronger than previous AlphaGo versions
- Far super-human skill

## Main Technical Changes in AlphaGo Zero

- New training method tailored for improving MCTS
- Self-learning from predicting searched moves and outcomes
- New network architecture: resnets
- New network architecture: combine policy and value nets into one net with two "heads"
- Does not need large distributed system anymore, strong performance on "one machine"

- Rules of Go, legal moves
- Hard limit of  $19 \times 19 \times 2 = 722$  moves on game length
- Tromp-Taylor scoring
- Input has same 2-d grid structure as Go board
- Uses rotation and reflection invariance of Go rules for training
- MCTS search parameters optimized

Some examples of knowledge used in many other Go programs, but not in Zero

- Avoid eye-filling moves (as in Go1)
- Patterns
- Tactics, atari, selfatari
- Human game records
- Rules for simulation policy No simulations outside of tree used in Zero

Zero has to learn many of these basics, and then much much more.

- Search still MCTS
- Used in two different ways:
  - For learning (new)
  - For playing
- The most impressive innovation in Zero is how search is used to improve learning, and learning in turn improves search

## Main Components of AlphaGo Zero -Knowledge

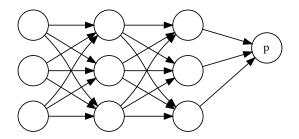
#### Knowledge

- All knowledge created by machine learning from self-play
- New network architecture
  - · Knowledge represented by deep residual neural net
  - Combines policy and value nets into one net with two "heads"
  - Both move and position evaluation learned together
- No more simulations (rollouts) to end of game!
  - MCTS tree growth controlled **only** by neural net knowledge (plus real end of game states reached in the tree)

- Deep residual neural network (He et al 2015)
- Learns two types of knowledge simultaneously
- Policy head
  - Learns good moves for the search
- Value head
  - Learns evaluation function probability of winning
- Most of network is shared between both (why?)

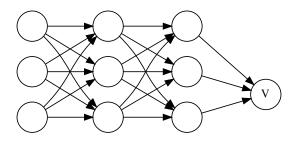
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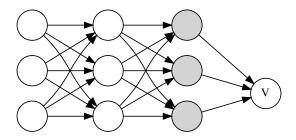
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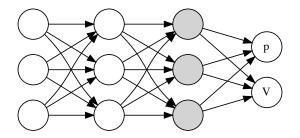
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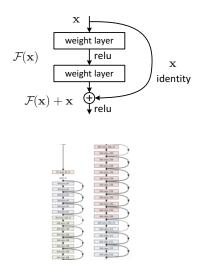


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## Deep Residual Neural Network (Resnet)



- Main idea: pass output of previous "block" directly through
- Each block learns a "delta", a small change to previous output
- Learning small changes is easier
- Can train really deep nets efficiently
- >100 layers in image recognition
- In theory, no greater representational power than DCNN
- In practice, learns better

## **Two-head Architecture**

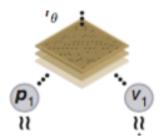


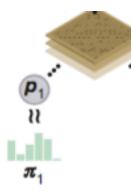
Image source: All further images from

AlphaGo Zero paper, unless stated

otherwise

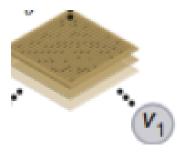
- $(p, v) = f_{\theta}(s)$
- Deep net
- Input Go position s
- Network weights  $\theta$
- Network computes function  $f_{\theta}(s)$
- Two outputs: (*p*, *v*)
  - *p* vector of move probabilities p(s, a) for each move *a*
  - v value of s

## Output 1 of Neural Network: Policy Head



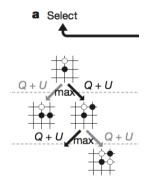
- Learns to predict what the search would do
- How frequently should each move be tried in MCTS?
- Learning goal: minimize cross-entropy between
  - Predicted probability of move
  - Frequency of move as selected by MCTS
- Cross-entropy: measures how well one probability distribution can predict another

## Output 2 of Neural Network: Value Head



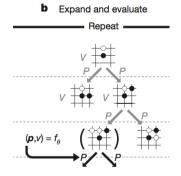
- Given a Go position
- Computes probability of winning
- Static evaluation function
- Trained from selfplay
- Learning goal: Minimize squared error between:
  - Predicted value v
  - Final result *z* of game

### MCTS in AlphaGo Zero - Move Selection



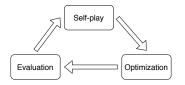
- In tree move selection
- Same formulas as in previous AlphaGo
  - Exploitation term Q
  - Exploration term u
- Meaning of Q is slightly changed
  - Value of simulation ending in in-tree state s = value head evaluation of s
  - No more simulation beyond the tree, no more evaluation component from rollouts

#### MCTS in AlphaGo Zero - Evaluation



- Node *s* expanded
- Single call to neural net
- $(p, v) = f_{\theta}(s)$
- *p* = vector of move probabilities,
  *p*(*s*, *a*) for all moves *a* from *s*
- v estimated value of s

## **Training Pipeline**



- Self-play: generate a collection of self-play game records by using MCTS + NN as both players
- Optimization: sample from game records to update the NNs
- Evaluation: play games between updated NN against previous NN. If the new NN wins 55% or more, replace NN used to generate self-play games

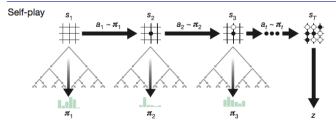
- Error measured by loss function
- Combines three terms
  - Error of policy head (cross entropy)
  - Error of value head
  - Regularization term to keep size of weights in check

## MCTS Visit Count and Policy $\pi$

Meaning of policy  $\pi$ :

- Run MCTS from some state s
- If move *a* was played *N*(*s*, *a*) times:
- $\pi_t(a) \propto N(s,a)^{1/\tau}$
- Probability is proportional to its "exponentiated visit count"
- Temperature parameter *τ* controls exploration of low-probability moves
- $\tau = 1$  for early game only, small for rest of game
- What does "proportional" mean?
- Compute values  $N(s, a)^{1/\tau}$  for all actions *a*, then divide by their sum to make them into probabilities

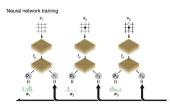
## Self-Play Games



- Play whole game
- For each state *s*<sub>t</sub> in game:
  - Run MCTS on st
  - Sample move to play according to number of simulations it received
    - Note difference to regular MCTS: exploration!
    - Regular MCTS would always pick the most-simulated move (exploitation)
- Finish game, get outcome z (win = +1 or loss = -1)
- Store tuples  $(s_t, \pi_t, z_t)$  for learning after end of game

- $(s_t, \pi_t, z_t)$
- *s*<sub>t</sub> = state at time step *t*
- Game = sequence of states  $s_1, s_2,...$
- π<sub>t</sub> = probability distribution derived from visit count of moves in MCTS of s<sub>t</sub>
- *z<sub>t</sub>* = result from current player's point of view (*z* or -*z*, negamax)

## Learning from Self-Play Games

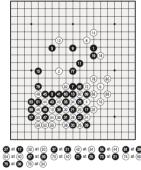


- After each game
- Randomly sample tuple (s, π, z) from all tuples stored from the game
- Adjust net weights θ by gradient descent:
- $(p, v) = f_{\theta}(s)$
- Make policy p better match  $\pi$
- Make value v better match z

- Most tests with 20 block resnet
- 4.9 million self-play games
- 1600 simulations / move in MCTS
- Update net in minibatches of 2048 game positions

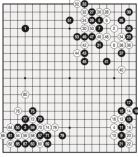
#### Zero After 3 Hours of Learning

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- Net learned for 3 hours
- Quick game, MCTS with 1600 simulations/move
- Learned about capturing stones
- Plays like human beginner
- Clearly better than random

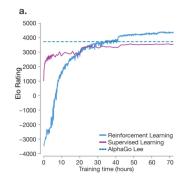
## Zero After 70 Hours of Learning



68 at 61

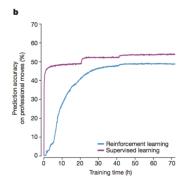
- 70 hours
- Quick game, MCTS with 1600 simulations/move
- Plays super-strong game of Go
- Complex strategies
- Exact score estimates, counting

## Comparing Early Learning - RL vs SL and AlphaGo Lee



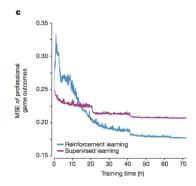
- After 72 hours of training
- Slow games vs AlphaGo Lee
- 2 hours per game per player
- Zero won 100 0

#### **Move Prediction**



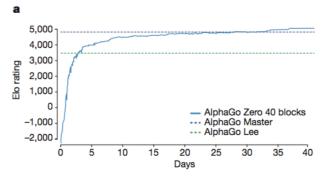
- Move prediction of human professional moves
- Learning improves, then plateaus
- Always stays below SL policy predictions (why?)
- Despite lower stats, most moves are very "human-like"

## Predicting the Outcome of Games



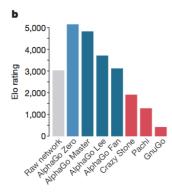
- Predict winner of human professional games
- MSE = mean square error between value net and real outcome
- Compare SL and RL value nets
- SL starts with big advantage
- RL becomes much better than SL with more training

# Compare Strength with AlphaGo Lee and Master



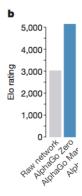
- Strongest version 40 residual blocks instead of 20
- Trained 29 million games, 40 days
- Learning compared to Elo strength of AlphaGo Lee and AlphaGo Master
- Match Zero 40-block vs Master: 89 wins 11 losses in slow games

## Results for Different AlphaGo Versions



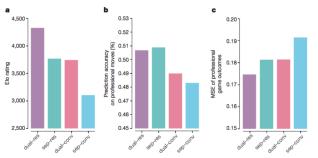
- Compares Elo for different versions of AlphaGo
- Fast games, 5 seconds / move
- Also compares Zero's "raw network" vs full Zero
- Raw network:
  - Evaluate current state s
  - Play highest probability move from policy head
  - No search
  - Almost as strong as AlphaGo Fan (with search)

## The Importance of Search



- Raw network vs AlphaGo Zero, 5 seconds / move
- With search 2000 Elo stronger
- That's 20 skill levels...
- Same gap as between top human professional and weak club player
- Stronger knowledge makes search even stronger
- No "diminishing returns", value of search remains very high

## **Comparing Network Architectures**



- Evaluate Elo strength, move prediction, MSE of game outcomes
- sep (separate networks) vs dual (one net, 2 heads)
- conv (DCNN) vs res (residual net)
- Clear benefit of dual architecture, sharing most of network
- Clear benefit of residual net over DCNN
- Only exception: sep better in move prediction

#### Some Limitations of AlphaGo

- AlphaGo only plays  $19 \times 19$  Go with 7.5 komi
- AlphaGo is not perfect no proofs, "mastering" vs solving the game
- $5 \times 5$  is still the largest solved square board size, since 2002 http://erikvanderwerf.tengen.nl/5x5/ 5x5solved.html
- AlphaGo is not open source we do not know many of the details

## Limitations of an AlphaGo-like Approach to Problem-Solving

- AlphaGo relies on having a perfect model of the game
- Exact rules of game, perfect scoring of outcome, full state of game known
- Model is used for creating many millions of self-play games
- Learning relies on having these games
- Big challenge: how to learn without perfect model
- MuZero (2019) addresses this with some success

- · Huge impact in media, outside of core AI community
- Often described as a major step towards "machine intelligence"
- Remember main limitation still needs an exact model to work well

- Huge impact in media, outside of core AI community
- Often described as a major step towards "machine intelligence"
- Remember main limitation still needs an exact model to work well
- Next:
  - Impact on AI and machine learning in general
  - Impact on heuristic search and computer game playing
  - Impact on human Go community

#### Impact on AI and Machine Learning

- Prime example of how combination of search, simulation and knowledge can achieve spectacular results
- Using deep learning:
  - Search improve knowledge
  - Knowledge improves search
  - Virtuous cycle, positive feedback loop
- Simulation has changed dramatically in-tree only, controlled completely by neural net evaluations, no more rollouts to end of game.
- AlphaGo (Zero) has dramatically shifted the landscape of what knowledge can do as part of a larger search-based system

#### Impact on AI and Machine Learning

- 10 years ago, with MCTS there was a similar shift in what search can do
- After current round of progress driven by knowledge, is it time for improving search methods again?
- Main questions:
  - Which other applications of deep learning can profit from adding search and simulation?
  - Which other applications of heuristic search can profit from deep learning?

# Impact on Heuristic Search and Computer Game-playing

- Dramatic shift to much stronger knowledge
- With each major advance in one of the three areas search, knowledge, simulations -
- · Need to rethink all heuristic search systems
- AlphaGo is only the beginning
- Much work ahead to fully exploit the power of stronger knowledge
- Can we learn stronger knowledge for other, harder problems
  - Video games (e.g. Atari games, Starcraft)
  - More open real-world problems with less well-defined rules

### Impact on Human Professional Go Community

- Human professionals study AlphaGo and other Al games intensely
- Try out many AlphaGo-inspired openings
- Some pros are worried for their jobs
- Less interest in human tournaments?
- Can pro-level phone replace human teachers?

### Impact on Human Amateur Go Community

- Temporary boost in excitement and visibility for the game of Go
- Having strong computer opponents (and online play) helps individuals in small communities without a Go club
- Will cheating become a problem, as in chess?
- Goals:
  - Turn programs into tools for teaching Go
  - Explain programs' moves in human terms

### Impact on Computer Go Community

- Mission accomplished? Game over?
- Taking chess as example
  - · Public interest in programming Go will fade
  - A core group of enthusiasts will keep going
  - Everyone will use programs as study tools
  - Level of humans will improve from studying with programs
- It is now possible for a single person to write a professional-level Go program in a year
- Recently, several such new programs

- Computer Go Today
- Applications to other games
- Other types of applications?
- · Current research: improving the techniques

- Half a dozen professional level Go programs
- Strongest: Tencent's FineArt
  - Can give top human professionals two stones handicap (!) in fast games
- Computer Go Server for automated testing
  - http://www.yss-aya.com/cgos/
- Computer Go Tournaments: http:

//www.computer-go.info/events/index.html

#### Leela Zero

- Strongest open source Go program:
- Public reimplementation of AlphaGo Zero
- Smaller network for faster learning
- Reached top pro level in a few months, still improving rapidly
- Community effort, over 400 participants donate CPU and GPU cycles
- Over 13 million games played
- Improved by 14000 Elo from random play at beginning

#### Leela Zero Learning Curve

#### Recent Strength Graph (Full view.)

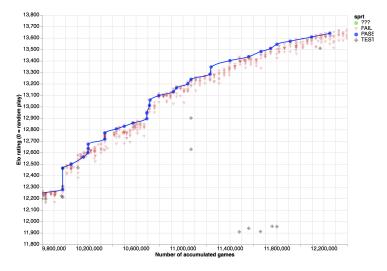


Image source: http://zero.sjeng.org

- Reviewed AlphaGo Zero in detail
- Discussed impact, state of computer Go after AlphaGo