Optimal Prediction cont. & Linear Regression

Textbook §6.2, §7.1

CMPUT 296: Basics of Machine Learning

Logistics

1. "In-class" quiz Thursday Oct 8 (next week!)

- Covers all material through section 7.1
- Tuesday class will be a review
- Quiz will be on eClass during a 24 hour period
- Random spot checks scheduled starting the following week
- Thought questions #2 also due October 8 2.
 - TQ#1 will be marked by the end of this week

Recap: Supervised Learning

- dataset $\mathcal{D} = \left\{ (\mathbf{x}_i, y_i) \right\}_{i=1}^n$
 - \mathscr{X} is the set of **observations**, and \mathscr{Y} is the set of **targets**
- **Classification** problems have discrete targets \bullet
- **Regression** problems have continuous targets

• Supervised learning problem: Learn a predictor $f: \mathcal{X} \to \mathcal{Y}$ from a

Recap: Optimal Prediction

to make predictions in a classification problem.

its expected cost $\mathbb{E}[C]$. The optimal predictor minimizes $\mathbb{E}[C]$.

$$\mathbb{E}[C] = \int_{\mathcal{X}} \sum_{y \in \mathcal{Y}} C$$

where $cost(\hat{y}, y)$ is the cost for predicting \hat{y} when the true value is y, and $C = \cot(f(X), Y)$ is a random variable.

- Suppose we know the true joint distribution $p(\mathbf{x}, y)$, and we want to use it
- The **optimal classification predictor** makes the **best** use of this function.
- As with the optimal estimator, we measure the quality of a predictor $f(\mathbf{x})$ by
 - $cost(f(\mathbf{x}), y) p(\mathbf{x}, y) d\mathbf{x},$

Outline

- Recap & Logistics 1.
- 2. Optimal Prediction for Regression
- 3. Irreducible and Reducible Error
- 4. MLE Formulation for Linear Regression

Cost Functions: Regression

- Two most common cost functions for regression:
 - 1. Squared error: $cost(\hat{y}, y) = (\hat{y} y)^2$
 - 2. Absolute error: $cost(\hat{y}, y) = |\hat{y} y|$
- Squared error penalizes large errors more heavily than absolute error
- Other possibilities that depend on the size of the target \bullet
 - E.g., percentage error: cost

$$(\hat{y}, y) = \frac{\left|\hat{y} - y\right|}{\left|y\right|}$$

Deriving Optimal Regressor for Squared Error

$$\mathbb{E}[C] = \int_{\mathcal{X}} \int_{\mathcal{Y}} \operatorname{cost} (f(\mathbf{x}), y) p(\mathbf{x}, y)$$
$$= \int_{\mathcal{X}} \int_{\mathcal{Y}} (f(\mathbf{x}) - y)^2 p(\mathbf{x}, y) dx$$
$$= \int_{\mathcal{X}} p(\mathbf{x}) \iint_{\mathcal{Y}} (f(\mathbf{x}) - y)^2 p(y)$$
$$\mathbb{E}[C \mid X = \mathbf{x}]$$
$$= \int_{\mathcal{X}} p(\mathbf{x}) \mathbb{E}[C \mid X = \mathbf{x}] d\mathbf{x}$$

 $dy d\mathbf{x}$

• Once again, we can directly optimize $\mathbb{E}[C \mid X = \mathbf{x}]$:

$$f^*(\mathbf{x}) = \arg\min_{\hat{y} \in \mathscr{Y}} g(\hat{y})$$

where

$$g(\hat{y}) = \int_{\mathscr{Y}} (\hat{y} - y)^2 p(y \mid \mathbf{x}) dx$$

 $dy d\mathbf{x}$





Deriving Opt
for Square
$$g(\hat{y}) = \int_{\mathscr{Y}} (\hat{y} - y)^2 p(y | \mathbf{x}) dx$$
$$\frac{\partial g(\hat{y})}{\partial \hat{y}} = 2 \int_{\mathscr{Y}} (\hat{y} - y) p(y | \mathbf{x}) dx$$
$$\iff \int_{\mathscr{Y}} \hat{y} p(y | \mathbf{x}) dy = \int_{\mathscr{Y}} y p(y | \mathbf{x}) dy$$
$$\implies \hat{y} \int_{\mathscr{Y}} p(y | \mathbf{x}) dy = \int_{\mathscr{Y}} y p(y | \mathbf{x}) dy$$
$$\implies \hat{y} = \int_{\mathscr{Y}} y p(y | \mathbf{x}) dy = \sum [Y]$$

timal Regressor ed Error, cont.

dy

 $\mathbf{x})\,dy=0$

So,

 \mathbf{x}) dy

 $f^*(\mathbf{x}) = \arg\min_{\hat{y} \in \mathscr{Y}} g(\hat{y})$ $= \mathbb{E}[Y \mid X = \mathbf{x}]$

 \mathbf{x}) dy

 $X = \mathbf{x}$

Generative Models

- Two approaches to learning $p(y | \mathbf{x})$:
 - **Discriminative:** Learn $p(y | \mathbf{x})$ directly 1.
 - 2. Generative: Learn $p(\mathbf{x} \mid y)$ and p(y), and exploit $p(y | \mathbf{x}) \propto p(\mathbf{x} | y)p(y)$

• The optimal prediction approach depends on (an estimate of) $p(y \mid \mathbf{x})$

• **Question:** What are the relative advantages of these two approaches?

Irreducible Error

What is our expected squared error when we use the optimal predictor? $f^*(\mathbf{x}) = \mathbb{E}[Y \mid X = \mathbf{x}], \text{ so}$ $\mathbb{E}[C] = \int_{\mathscr{V}} p(\mathbf{x}) \int_{\mathscr{V}} (f^*(\mathbf{x}) - y)^2 \mu$ $= \int_{\mathcal{X}} p(\mathbf{x}) \int_{\mathcal{U}} \left(\mathbb{E}[Y \mid X = \mathbf{x}] \right)$ $= \int_{\mathcal{X}} p(\mathbf{x}) \operatorname{Var}[Y \mid X = \mathbf{x}] d\mathbf{x}$

$$p(y \mid X = \mathbf{x}) \, dy \, d\mathbf{x}$$

$$[x] - y)^2 p(y \mid X = \mathbf{x}) \, dy \, d\mathbf{x}$$

Reducible Error

$\mathbb{E}[C \mid X] = \mathbb{E}\left[\left(f(\mathbf{x}) - Y\right)^2 \mid X = \mathbf{x}\right] = \mathbb{E}\left[\left(f(\mathbf{x}) - \mathbb{E}[Y \mid X = \mathbf{x}]\right)^2\right]$ $+ \left(\mathbb{E}[Y \mid X = \mathbf{x}] - Y \right)^2$

We'll take expectation again at the end to get to $\mathbb{E}[C] = \mathbb{E}[\mathbb{E}[C|X]]$

What is our expected squared error when we use a suboptimal predictor?

$$\mathbb{E}\left[\left(f(\mathbf{x}) - \mathbb{E}[Y \mid X = \mathbf{x}] + \mathbb{E}[Y \mid X = \mathbf{x}] - Y\right)^2 \middle| X = \mathbf{x}\right]$$
$$|)^2 + 2\left[\left(f(\mathbf{x}) - \mathbb{E}[Y \mid X = \mathbf{x}]\right) \left(\mathbb{E}[Y \mid X = \mathbf{x}] - \mathbb{E}[Y \mid X = \mathbf{x}]\right) - \mathbb{E}[Y \mid X = \mathbf{x}]\right]$$
$$= 0$$



Reducible Error: Middle Term is 0

$\mathbb{E}\left[\left(f(\mathbf{x}) - \mathbb{E}[Y \mid X = \mathbf{x}]\right)\left(\mathbb{E}[Y \mid X = \mathbf{x}]\right)\right]$ $= \left(f(\mathbf{x}) - \mathbb{E}[Y \mid X = \mathbf{x}] \right) \mathbb{E} \left[\left(\mathbb{E}[Y \mid X = \mathbf{x}] \right) \mathbb{E} \right]$ $= \left(f(\mathbf{x}) - \mathbb{E}[Y \mid X = \mathbf{x}] \right) \left(\mathbb{E}[Y \mid X = \mathbf{x}] \right)$ $= \left(f(\mathbf{x}) - \mathbb{E}[Y \mid X = \mathbf{x}] \right) \mathbf{0}$ = ()

$$X = \mathbf{x}] - Y \Big| X = \mathbf{x} \Big|$$
$$Y | X = \mathbf{x}] - Y \Big| X = \mathbf{x} \Big|$$
$$X = \mathbf{x}] - \mathbb{E}[Y | X = \mathbf{x}] \Big)$$

Reducible Error

What is our expected squared error when we use a suboptimal predictor? $\mathbb{E}[C \mid X] = \mathbb{E}\left| \left(f(\mathbf{x}) - Y \right)^2 \right| X = \mathbf{x} \right| =$ $= \mathbb{E} \left| \left(f(\mathbf{x}) - \mathbb{E}[Y \mid X = \mathbf{x}] \right) \right|$ $+ \left(\mathbb{E}[Y \mid X = \mathbf{x}] - Y \right)^2$ $= \mathbb{E} \left| \left(f(\mathbf{x}) - \mathbb{E}[Y \mid X = \mathbf{x}] \right) \right|$ $\mathbb{E}\left[\mathbb{E}[C|X]\right] = \mathbb{E}\left[\left(f(X) - \mathbb{E}[Y|X]\right)\right]$ $\mathbb{E}[C] = \mathbb{E}\left| \left(f(X) - f^*(X) \right)^2 \right| + \mathbb{E} \left| \left(f(X) - f^*(X) \right)^2 \right| + \mathbb{E} \left| f(X) - f^*(X) \right|^2 \right|$ Reducible error Irreducible error

$$\mathbb{E}\left[\left(f(\mathbf{x}) - \mathbb{E}[Y \mid X = \mathbf{x}] + \mathbb{E}[Y \mid X = \mathbf{x}] - Y\right)^2 \mid X = \mathbf{x}\right]$$
$$)^2 + 2\left[\left(f(\mathbf{x}) - \mathbb{E}[Y \mid X = \mathbf{x}]\right) \left(\mathbb{E}[Y \mid X = \mathbf{x}] - \mathbf{x}\right]$$
$$= 0$$
$$X = \mathbf{x}\right]$$
$$)^2 + \left(\mathbb{E}[Y \mid X = \mathbf{x}] - Y\right)^2 \mid X = \mathbf{x}\right]$$
$$)^2\right] + \mathbb{E}\left[\left(\mathbb{E}[Y \mid X] - Y\right)^2\right]$$
$$(f^*(X) - Y)^2\right]$$



Summary

- Supervised learning problem: Learn a predictor $f : \mathcal{X} \to \mathcal{Y}$ from a dataset $\mathcal{D} = \{(\mathbf{x}_i, y_i)\}_{i=1}^n$
 - ${\mathcal X}$ is the set of <code>observations</code>, and ${\mathcal Y}$ is the set of <code>targets</code>
- Classification problems have discrete targets
- Regression problems have continuous targets
- Predictor performance is measured by the expected $cost(\hat{y}, y)$ of predicting \hat{y} when the true value is y
- An optimal predictor for a given distribution minimizes the expected cost
- Even an optimal predictor has some irreducible error.
 Suboptimal predictors have additional, reducible error

Linear Predictors

A linear predictor is a function of the form

$$f(\mathbf{x}) = w_0 + w_1 x_1 + \dots$$

- Predict a linear combination of weights w and features x
- Linear regression: finding the best parameters $\mathbf{w} \in \mathbb{R}^{d+1}$
- **Question:** What criterion should we use to pick **W**? lacksquare



Suppose that our dataset $\mathscr{D} = \{(\mathbf{x}_i, y_i)\}_{i=1}^n$ was drawn as follows:

1. $\mathbf{X}_i \stackrel{i.i.d.}{\sim} p(\mathbf{X})$ 2. $\epsilon_i \stackrel{i.i.d.}{\sim} \mathcal{N}(0,\sigma^2)$

3. $y_i = \sum_{j=1}^{d} \omega_j x_{ij} + \epsilon_i$ j=0

Gaussian Error Model

Question: what is the distribution of Y?



Linear Regression as Model Estimation

- We now have a parametric family of conditional models to select from: $\mathscr{F} = \left\{ p(\cdot \mid \mathbf{x}) = \mathscr{N}(\mathbf{w}^T \mathbf{x}, \sigma^2) \mid \mathbf{w} \in \mathbb{R}^{d+1} \right\}.$
 - (Equivalently, need to select a parameter vector $\mathbf{w} \in \mathbb{R}^{d+1}$ that identifies a conditional model in the family)
- Once we have selected a model, we can use it to make predictions
- Question: How should we use an estimated model $p(y \mid \mathbf{x}, \mathbf{w})$ for prediction?

MLE for Linear Regression



$$= \arg \min_{\mathbf{w} \in \mathbb{R}^{d+1}} - \sum_{i=1}^{n} \ln p(y_i \mid \mathbf{x}_i, \mathbf{w})$$
$$= \arg \min_{\mathbf{w} \in \mathbb{R}^{d+1}} - \sum_{i=1}^{n} \ln \left[\frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(y_i - \mathbf{w}^T \mathbf{x}_i)}{2\sigma^2}\right) \frac{1}{\sqrt{2\sigma^2}} \frac{1}{\sqrt$$



MLE for Linear Regression cont.

$$\mathbf{w}_{\mathsf{MLE}} = \arg\min_{\mathbf{w}\in\mathbb{R}^{d+1}} - \sum_{i=1}^{n} \ln\left[\frac{1}{\sqrt{2\pi\sigma^2}}\exp\left(-\frac{1}{2\sigma^2}\right)\right]$$
$$= \arg\min_{\mathbf{w}\in\mathbb{R}^{d+1}} \sum_{i=1}^{n} \left[-\ln\sqrt{2\pi\sigma^2} - \frac{(y_i - y_i)}{2\sigma^2}\right]$$
$$= \arg\min_{\mathbf{w}\in\mathbb{R}^{d+1}} \sum_{i=1}^{n} \ln\sqrt{2\pi\sigma^2} + \sum_{i=1}^{n} \frac{(y_i - \mathbf{w})^2}{2\sigma^2}$$
$$= \arg\min_{\mathbf{w}\in\mathbb{R}^{d+1}} \sum_{i=1}^{n} \frac{(y_i - \mathbf{w}^T\mathbf{x})^2}{2\sigma^2}$$



Constant w.r.t. w

Prediction with MLE Model

- where $\mathbf{w}_{\text{MLE}} = \arg \min_{\mathbf{w} \in \mathbb{R}^{d+1}} \sum_{i=1}^{n} (y_i \mathbf{w}^T \mathbf{x})^2$
- **Question:** How should we use this estimated model for prediction?
- **Question:** What is the expected value of Y conditional on $X = \mathbf{x}$?

We have an estimated model of the process: $Y \sim \mathcal{N}\left(\mathbf{w}_{MLE}^T \mathbf{x}, \sigma^2\right)$,

• Use the optimal regression predictor assuming this is the correct model:

 $f(\mathbf{x}) = \mathbb{E}[Y \mid X = \mathbf{x}]$

We just minimize the sum of squared errors on our dataset $\mathscr{D}!$

Question: What are the advantages of doing the MLE derivation rather than just directly minimizing error on the dataset?

- 1. It makes the **assumptions** behind the process clear:
 - underlying linear relationship between y_i and \mathbf{x}_i
 - i.i.d. errors in y_i
 - no errors in \mathbf{X}_i
 - **noise** (error term) ϵ_i is a zero-mean Gaussian
 - noise ϵ_i is independent of the features \mathbf{X}_i

Ordinary Least Squares $\mathbf{w}_{\mathsf{MLE}} = \arg\min_{\mathbf{w}\in\mathbb{R}^{d+1}}\sum_{i=1}^{n} (y_i - \mathbf{w}^T \mathbf{x})^2$

2. It is a **general** approach:

- A good objective for other distributions of $p(y \mid \mathbf{x})$ is not as obvious
- But the MLE approach will work for any distribution









Summary

A linear predictor has the form $f(\mathbf{x}) =$

Traditional approach: Find the linear predictor that minimizes squared error on the dataset (aka Ordinary Least Squares)

Probabilistic approach:

- 1. Assume i.i.d. Gaussian noise: Y
- 2. Use MLE to estimate model from resulting parametric family $\mathcal{F} = \left\{ p(\cdot \mid \mathbf{x}) = \mathcal{N}(\mathbf{w}^T \mathbf{x}, \sigma^2) \mid \mathbf{w} \in \mathbb{R}^{d+1} \right\}$
- 3. Use the optimal predictor for the estimated model \mathbf{W}^* : $f^*(\mathbf{x}) = \mathbb{E}[Y \mid X = \mathbf{x}] = \mathbf{w}^T \mathbf{x}$

$$w_0 + w_1 x_1 + \dots + w_d x_d = \sum_{j=0}^d w_j x_j = \mathbf{w}^T \mathbf{x}$$

~
$$\mathcal{N}(\boldsymbol{\omega}^T \mathbf{x}, \boldsymbol{\sigma}^2)$$