Inference in Belief Networks

CMPUT 261: Introduction to Artificial Intelligence

P&M §8.4

Assignments

- Assignment #1: Late deadline was last night
 - Marking should be done by next week
- Assignment #2 will be posted today by midnight
 - Due Feb 29/2024 at 11:59pm

Lecture Outline

- Recap
- 2. Factor Objects
- 3. Variable Elimination
- 4. Further Optimizations

After this lecture, you should be able to:

- encode a factoring of a joint distribution as a collection of factor objects for variable elimination
- define the factor operations used in variable elimination
- describe the high-level steps of variable elimination
- compare efficiency of different variable orderings for variable elimination
- trace an execution of variable elimination

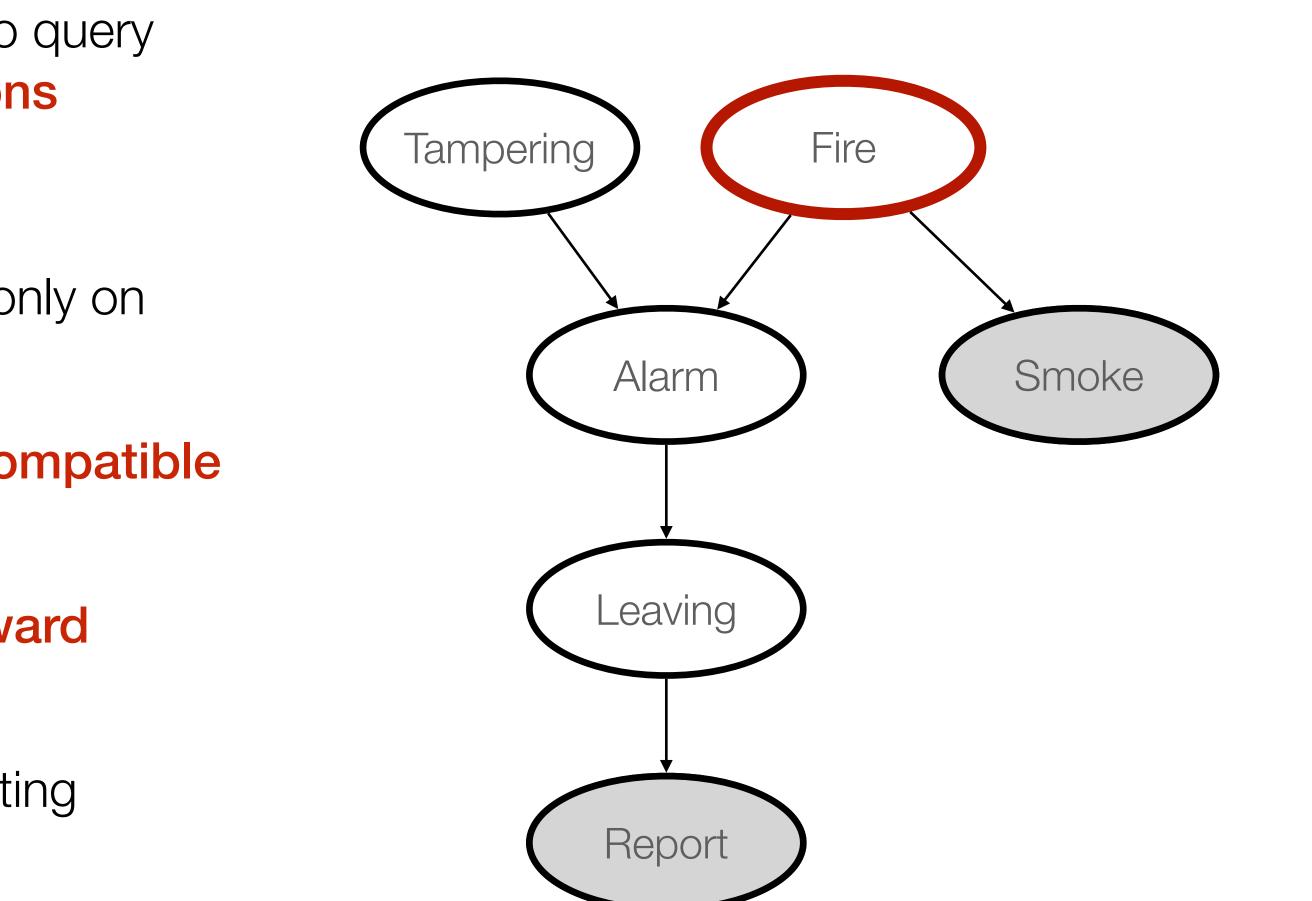
Recap: Belief Networks

Definition: A belief network (or Bayesian network) consists of:

- A directed acyclic graph, with each node labelled by a random variable
- 2. A **domain** for each random variable
- 3. A conditional probability table for each variable given its parents
- The graph represents a specific **factorization** of the full **joint distribution**
- **Key Property:** Every node is **independent** of its **non-descendants**, **conditional** on its **parents**

Recap: Queries

- The most common task for a belief network is to query posterior probabilities given some observations
- Easy cases:
 - Posteriors of a single variable conditional only on parents
 - Joint distributions of variables early in a compatible variable ordering
- Typically, the observations have no straightforward relationship to the target
- This lecture: mechanical procedure for computing arbitrary queries

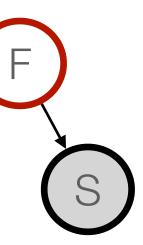


A (Simplistic) Algorithm for Queries \checkmark

P(F, T, A, L, S, R) = P(F)P(T)P(A | T, F)P(L | A)P(S | F)P(R | L)Query: P(F | S = 1, R = 1)

1. Condition: P(F, T, A, L, S = 1, R = 1) = P(F)P(T)P(A | T, F)P(S = 1 | F)P(L | A)P(R = 1 | L)2. Normalize: $P(F, T, A, L | S = 1, R = 1) = \frac{P(F, T, A, L, S = 1, R = 1)}{\sum_{f \in \text{dom}(F), P(F = f, T = t, A = a, L = l, S = 1, R = 1)} \sum_{\substack{t \in \text{dom}(I), \\ l \in \text{dom}(L)}} \frac{P(F = f, T = t, A = a, L = l, S = 1, R = 1)}{\sum_{f \in \text{dom}(L)}}$

3. Marginalize: $P(F \mid S = 1, R = 1) = \sum_{\substack{t \in \text{dom}(T), \\ a \in \text{dom}(A), \\ l \in \text{dom}(L)}} P(F, T = t, A = a, L = l \mid S = 1, R = 1)$



Factor Object

- The Variable Elimination algorithm exploits the factorization of a joint probability distribution encoded by a belief network in order to answer **queries**
- A factor object is a function $f(X_1, \ldots, X_k)$ from random variables to a real number
- Input: factors representing the conditional probability tables from the belief network $P(L \mid A)P(S \mid F)P(A \mid T, F)P(T)P(F)$

becomes factor objects

- **Output:** A new factor encoding the target posterior distribution E.g., $f_{12}(T)$.
- $f_1(L,A)f_2(S,F)f_3(A,T,F)f_4(T)f_5(F)$

Conditional Probabilities as Factor Objects

• A conditional probability $P(Y \mid X_1, \ldots, X_n)$ is a factor object $f(Y, X_1, \ldots, X_n)$ that obeys the **constraint**:

 $\forall v_1 \in dom(X_1), v_2 \in dom(X_2), \dots, v_n$

- Answer to a query is a factor object **constructed** by applying **operations** to the input factors
 - Operations on factor objects are *not* guaranteed to **maintain** this constraint!
 - Solution: **Don't sweat it**!
 - Operate on **unnormalized probabilities** during the computation
 - **Normalize** at the end of the algorithm to re-impose the constraint

$$\in dom(X_n): \left[\sum_{\substack{y \in dom(Y)}} f(y, v_1, \dots, v_n)\right] = 1.$$

Conditioning

Conditioning is an operation on a **single factor**

its inputs fixed

Definition:

For a factor f_1

$$\begin{aligned} &X_k \end{pmatrix}, \text{ conditioning on } X_i = v_i \text{ yields a new factor} \\ &f_2(X_1, \dots, X_{i-1}, X_{i+1}, \dots, X_k) = (f_1)_{X_i = v_i} \\ &I_1, \dots, v_{i-1}, v_{i+1}, \dots, v_k \text{ in the domain of } X_1, \dots, X_{i-1}, X_{i+1}, \dots, X_k, \\ &V_{i-1}, v_{i+1}, \dots, v_k \end{pmatrix} = f_1(v_1, \dots, v_{i-1}, \mathbf{v_i}, v_{i+1}, \dots, v_k). \end{aligned}$$

such that for

$$f_1(X_1, ..., X_k), \text{ conditioning on } X_i = v_i \text{ yields a new factor}$$

$$f_2(X_1, ..., X_{i-1}, X_{i+1}, ..., X_k) = (f_1)_{X_i = v_i}$$
all values $v_1, ..., v_{i-1}, v_{i+1}, ..., v_k$ in the domain of $X_1, ..., X_{i-1}, X_{i+1}, ..., X_k$

$$f_2(v_1, ..., v_{i-1}, v_{i+1}, ..., v_k) = f_1(v_1, ..., v_{i-1}, \mathbf{v_i}, v_{i+1}, ..., v_k).$$

Constructs a new factor that returns the values of the original factor with some of

Conditioning Example

 f_1 С Β value Α F F F 0.1 F 0.88 F 0.12 F F 0.45 F Т Т 0.7 F F 0.66 F Т 0.1 F 0.25 Т

 $f_2(A, B) = f_1(A, B, C)_{C=true}$

	f_2	
Α	В	value
F	F	0.88
F	Т	0.45
Т	F	0.66
Т	Т	0.25

Multiplication

Multiplication is an operation on two factors

• Constructs a new factor that return factor by its arguments

Definition:

For two factors $f_1(X_1, \ldots, X_j, Y_1, \ldots, Y_k)$ multiplication of f_1 and f_2 yields a new factor

$$(f_1 \times f_2) = f_3(X_1, \dots, X_j, Y_1, \dots, Y_k, Z_1, \dots, Z_\ell)$$

such that for all values $x_1, \ldots, x_j, y_1, \ldots, y_k, z_1, \ldots, z_{\ell'}$

$$f_3(x_1, \dots, x_j, y_1, \dots, y_k, z_1, \dots, z_\ell) = f_1$$

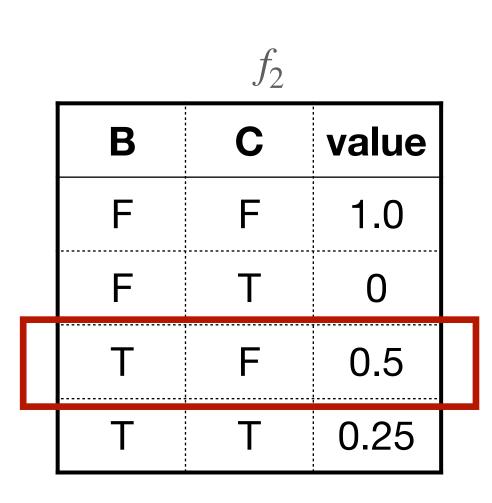
Constructs a new factor that returns the product of the rows selected from each

and
$$f_2(Y_1, ..., Y_k, Z_1, ..., Z_\ell)$$
,
actor

 $f_1(x_1, \ldots, x_j, y_1, \ldots, y_k) f_2(y_1, \ldots, y_k, z_1, \ldots, z_\ell).$

Multiplication Example

 $f_3(A, B, C) = f_1(A, B) \times f_2(B, C)$



	f_1		-
Α	В	value	
F	F	0.1	
F	Т	0.2	
Т	F	0.3	
Т	Т	0.4	

f_3					
Α	В	С	value		
F	F	F	0.1		
F	F	Т	0		
F	Т	F	0.1		
F	Т	Т	0.05		
Т	F	F	0.3		
Т	F	Т	0		
Т	Т	F	0.2		
Т	Τ	Т	0.1		

Summing Out

Summing out is an operation on a single factor

factor

Definition:

For a factor $f_1(X_1, \ldots, X_k)$, summing out a variable X_i yields a new factor

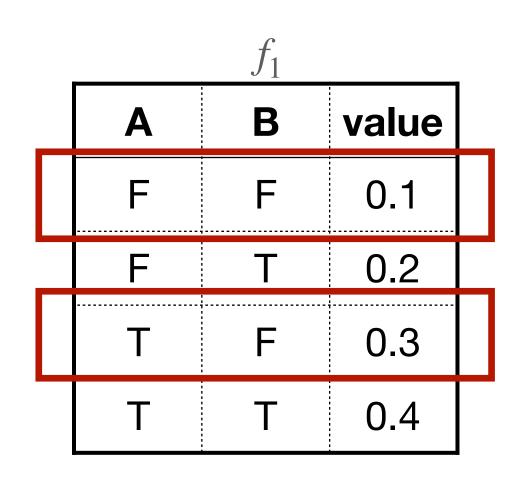
$$f_2(X_1, \dots, X_{i-1}, X_{i+1}, \dots, X_k) = \left(\sum_{X_i} f_1\right)$$

such that for all values $v_1, ..., v_{i-1}, v_{i+1}, ..., v_k$ in the domain of $X_1, ..., X_{i-1}, X_{i+1}, ..., X_k$

$$f_2(v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_k) = \sum_{\mathbf{v}_i \in dom(X_i)} f_1(v_1, \dots, v_{i-1}, \mathbf{v}_i, v_{i+1}, \dots, v_k).$$

• Constructs a new factor that returns the sum over all values of a random variable of the original

Summing Out Example



 $f_2(B) = \sum f_1(A, B)$ A

f_2		
В	value	
F	0.4	
Т	0.6	

• Given observations $Y_1 = v_1, \dots, Y_k = v_k$ and query variable Q, we want

$$P(Q \mid Y_1 = v_1, \dots, Y_k = v_k) = \frac{P(Q, Y_1 = v_1, \dots, Y_k = v_k)}{\sum_{q \in dom(Q)} P(Q = q, Y_1 = v_1, \dots, Y_k = v_k)}$$

- Basic idea of variable elimination:
 - Condition on observations by **conditioning**
 - Construct joint distribution factor by **multiplication**
 - З.
 - 4. Normalize at the end
- Doing these steps in order is **correct** but not **efficient** lacksquare
- Efficiency comes from **interleaving** the order of operations

Variable Elimination

Remove unwanted variables (neither query nor observed) by summing out

Sums of Products

- Construct joint distribution factor by multiplication
- Remove unwanted variables (neither query nor observed) by summing out

The computationally intensive part of variable elimination is computing sums of products

Example: multiply factors $f_1(Q, A, B, C)$, $f_2(C, D, E)$; sum out A, E

- 1. $f_3(Q, A, B, C, D, E) = f_1(Q, A, B, C) \times f_2(C, D, E) : 2^6$ multiplications
- 2. $f_4(Q, B, C, D) = \sum f_3(Q, A, B, C, D, E)$: 3×16 additions

Total: **112** computations

(*) For all numerical examples, we assume binary domains



Efficient Sums of Products

We can reduce the number of computations required by changing their order.

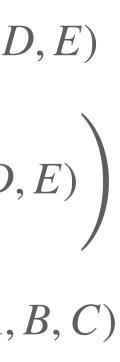
 $\sum f_1(Q, A, B, C) \times f_2(C, D, E)$

1. $f_3(C,D) = \sum_E f_2(C,D,E)$: 2² additions

- 2. $f_4(Q, B, C) = \sum_A f_1(Q, A, B, C)$: 2³ additions
- 3. $f_5(Q, B, C, D) = f_3(Q, B, C) \times f_4(B, C, D) : 2^4$ multiplications

Total: 28 computations

 $\sum \sum f_1(Q, A, B, C) \times f_2(C, D, E)$ $\begin{array}{ccc}
\overline{A} & \overline{E} \\
= & \sum_{A} f_1(Q, A, B, C) \left(\sum_{E} f_2(C, D, E) \right) \\
= & \left(\sum_{A} f_1(Q, A, B, C) \right) \times \left(\sum_{E} f_2(C, D, E) \right) \\
= & \left(\sum_{E} f_2(C, D, E) \right) \sum_{A} f_1(Q, A, B, C) \\
\end{array}$



Variable Elimination Algorithm

Input: query variable Q; set of variables Vs; observations O; factors Ps representing conditional probability tables

Fs := Ps

for each X in $Vs \setminus \{Q\}$ according to some elimination ordering: $Rs := \{F \in Fs \mid F \text{ involves } X\}$

if $X \in O$:

for each $F \in Rs$:

F' := F conditioned on observed value of X $Fs := (Fs \setminus \{F\}) \cup \{F'\}$

else:

T := product of factors in RsN := sum X out of T $Fs := (Fs \setminus Rs) \cup \{N\}$ T := product of factors in FsN := sum Q out of Treturn T/N (i.e., normalize T)

Variable Elimination Example: Conditioning

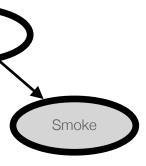
Query: P(T | S = 1, R = 1)Variable ordering: S, R, F, A, L

 $P(T, F, A, S, L, R) = P(T)P(F)P(A \mid T, F)P(S \mid F)P(L \mid A)P(R \mid L)$

Construct **factors** for each table: { $f_0(T), f_1(F), f_2(T, A, F), f_3(S, F), f_4(L, A), f_5(R, L)$ }

Condition on S: $f_6 = (f_3)_{S=1}$ { $f_0(T), f_1(F), f_2(T, A, F), f_6(F), f_4(L, A), f_5(R, L)$ }

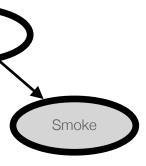
Condition on $R: f_7 = (f_5)_{R=1}$ { $f_0(T), f_1(F), f_2(T, A, F), f_6(F), f_4(L, A), f_7(L)$ }



Alarm

Variable Elimination Example: Elimination

Query: P(T | S = 1, R = 1)Variable ordering: S, R, F, A, L{ $f_0(T), f_1(F), f_2(T, A, F), f_6(F), f_4(L, A), f_7(L)$ } Sum out *F* from product of f_1, f_2, f_6 : $f_8 = \sum_{i=1}^{n} (f_1 \times f_2 \times f_6)$ { $f_0(T), f_8(T, A), f_4(L, A), f_7(L)$ } Sum out A from product of f_8, f_4 : $f_9 = \sum (f_8 \times f_4)$ $f_0(T), f_9(T, L), f_7(L)$ Sum out *L* from product of $f_9, f_7: f_{10} = \sum (f_9 \times f_7)$ $\{f_0(T), f_{10}(T)\}$



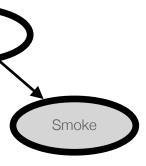
Alarm

Variable Elimination Example: Normalization

Query: P(T | S = 1, R = 1)Variable ordering: *S*, *R*, *F*, *A*, *L* $\{f_0(T), f_{10}(T)\}$

Product of remaining factors: $f_{11} = f_0 \times f_{10}$ $\{f_{11}(T)\}$

Normalize by division: $\Delta_T J_{11}(I)$



Tampering

Alarm

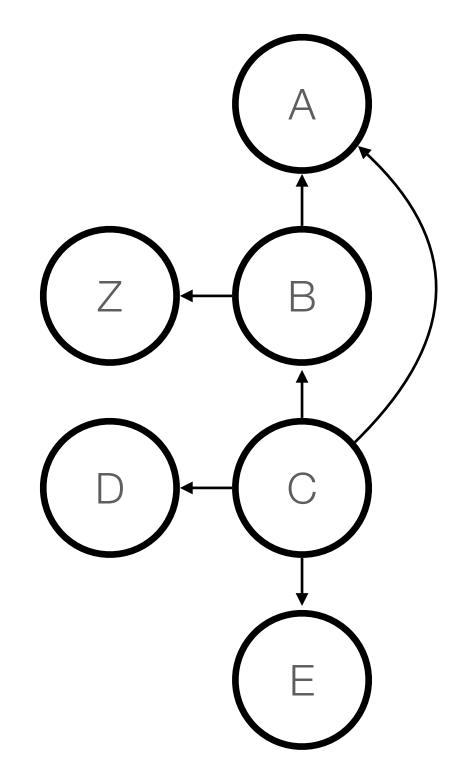
Optimizing Elimination Order

- Variable elimination exploits efficient sums of products on a factored joint distribution
- The elimination order of the variables affects the efficiency of the algorithm
- Finding an optimal elimination ordering is NP-hard
- Heuristics (rules of thumb) for good orderings:
 - Observations first: Condition on all of the observed variables first
 - Min-factor: At every stage, select the variable that constructs the smallest new factor
 - Problem-specific heuristics

Min-Factor Example

Factors: { $f_1(Z, B), f_2(B, C), f_3(C), f_4(D, C), f_5(A, B, C), f_6(E, C)$ }

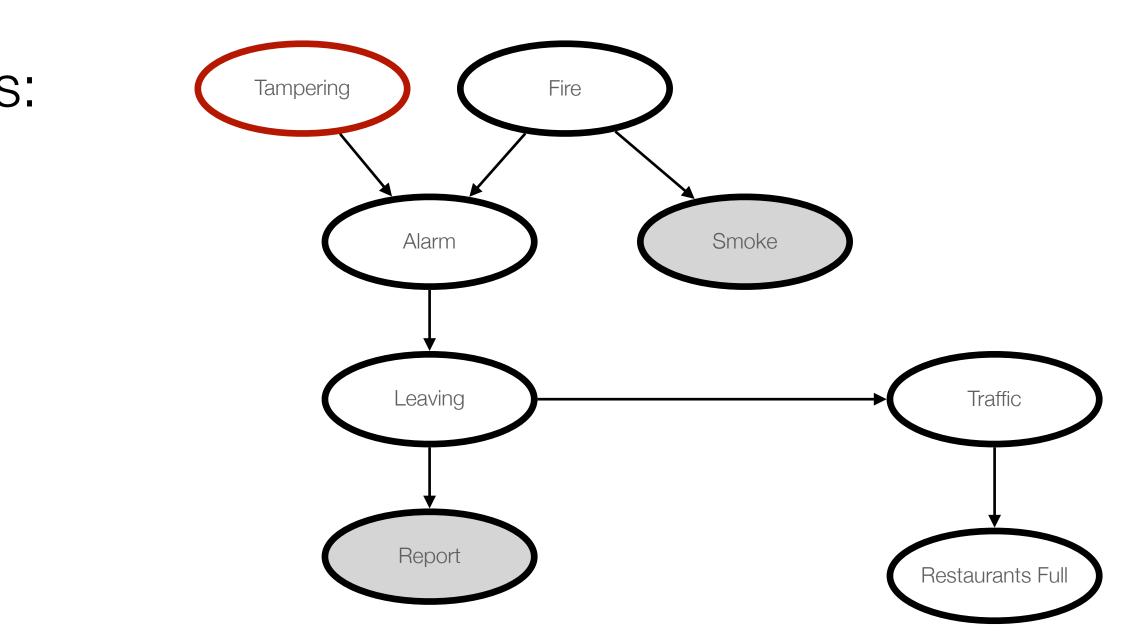
- Which variable creates the largest new factor when it is eliminated? \bullet • C: Remove $f_2(B, C), f_3(C), f_4(D, C), f_5(A, B, C), f_6(E, C),$
- Add $f_7(A, B, D, E)$
- Which variable creates the **smallest** new factor when it is eliminated? \bullet • Z: Remove $f_1(Z, B)$, add $f_7(B)$
- - (*E* would also work)
 - Number of **rows** is what matters, not number of arguments



Optimization: Pruning

- that are neither observed nor queried
 - Summing them out for **free**
- We can **repeat** this process:

• The structure of the graph can allow us to drop leaf nodes



Optimization: Preprocessing

the same variables, we can **preprocess** our graph; e.g.:

- 1. Precompute the joint distribution of all the variables we will observe and/or query
- 2. Precompute conditional distributions for our exact queries

Finally, if we know that we are always going to be observing and/or querying

Summary

- Variable elimination is an algorithm for answering queries based on a \bullet belief network
- distribution
 - Conditioning
 - Multiplication 2.
 - 3. Summing out
 - (Once only): Normalization 4.
- \bullet
 - **Optimal** order of operations is **NP-hard** to compute

Operates by using three operations on factors to reduce graph to a single posterior

Distributes operations more efficiently than taking full product and then summing out

Additional optimization techniques: heuristic ordering, pruning, precomputation

Upcoming event:

Cybersecurity, Hacking, and Digital Security Club

HACK-FHE COMPUTER **OPEN THE BOX**



Are you ready to embark on a journey into the exciting world of cybersecurity? You are invited to CHADS' annual cybersecurity competition, Hack the **Computer Open the Box!**

RSVP now!

While this event is beginner friendly, having some background knowledge would be beneficial. :)

There will be food, drinks, prizes !!

FEB 24TH 1:00 PM @ ETLC E5-013



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