

Calculus Refresher

CMPUT 366: Intelligent Systems

GBC §4.1, 4.3

Lecture Outline

1. Recap
2. Gradient-based optimization
3. Numerical issues

Recap: Bayesian Learning

- In Bayesian Learning, we learn a **distribution** over models instead of a **single model**
- **Model averaging** to compute predictive distribution
- **Prior** can encode **bias** over models (like regularization)
- **Conjugate** models: can compute everything analytically

Recap: Monte Carlo

- Often we **cannot directly estimate** expectations from our model
 - Example: non-conjugate Bayesian models
- **Monte Carlo estimates:** Use a random sample from the distribution to estimate expectations by sample averages
 1. Use an easier-to-sample **proposal** distribution instead
 2. Sample parts of the model **sequentially**

Loss Minimization

In supervised learning, we choose a **hypothesis** to **minimize** a **loss function**

Example: Predict the **temperature**

- *Dataset:* temperatures $y^{(i)}$ from a random sample of days
- *Hypothesis class:* Always predict the **same value** μ
- *Loss function:*

$$L(\mu) = \frac{1}{n} \sum_{i=1}^n (y^{(i)} - \mu)^2$$

Optimization

Optimization: finding a value of x that **minimizes** $f(x)$

$$x^* = \arg \min_x f(x)$$

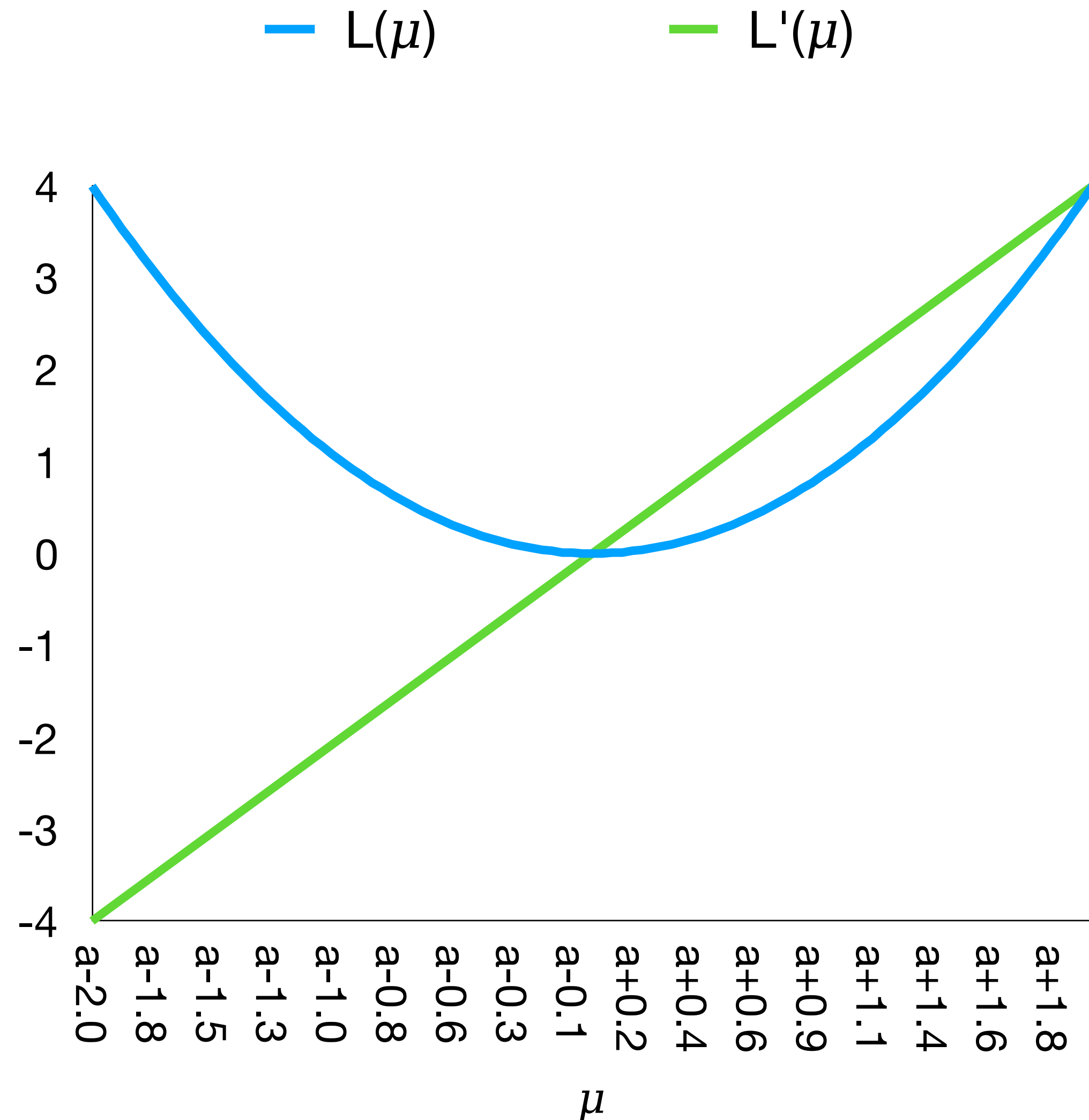
- Temperature example: Find μ that makes $L(\mu)$ small

Gradient descent: Iteratively move from current estimate in the direction that makes $f(x)$ **smaller**

- For **discrete** domains, this is just **hill climbing**:
Iteratively choose the **neighbour** that has minimum $f(x)$
- For **continuous** domains, neighbourhood is less well-defined

Derivatives

- The **derivative** $f'(x) = \frac{d}{dx}f(x)$ of a function $f(x)$ is the **slope** of f at point x
- When $f'(x) > 0$, f **increases** with small enough increases in x
- When $f'(x) < 0$, f **decreases** with small enough increases in x



Multiple Inputs

Example:

Predict the temperature **based on** pressure and humidity

- *Dataset:* $(x_1^{(1)}, x_2^{(1)}, y^{(1)}), \dots, (x_1^{(m)}, x_2^{(m)}, y^{(m)}) = \{(\mathbf{x}^{(i)}, y^{(i)}) \mid 1 \leq i \leq m\}$
- *Hypothesis class:* Linear regression: $h(\mathbf{x}; \mathbf{w}) = w_0 + w_1x_1 + w_2x_2$
- *Loss function:*

$$L(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n (y^{(i)} - h(\mathbf{x}^{(i)}; \mathbf{w}))^2$$

Partial Derivatives

Partial derivatives: How much does $f(\mathbf{x})$ change when we **only change one** of its inputs x_i ?

- Can think of this as the derivative of a **conditional** function $g(x_i) = f(x_1, \dots, \mathbf{x}_i, \dots, x_n)$:

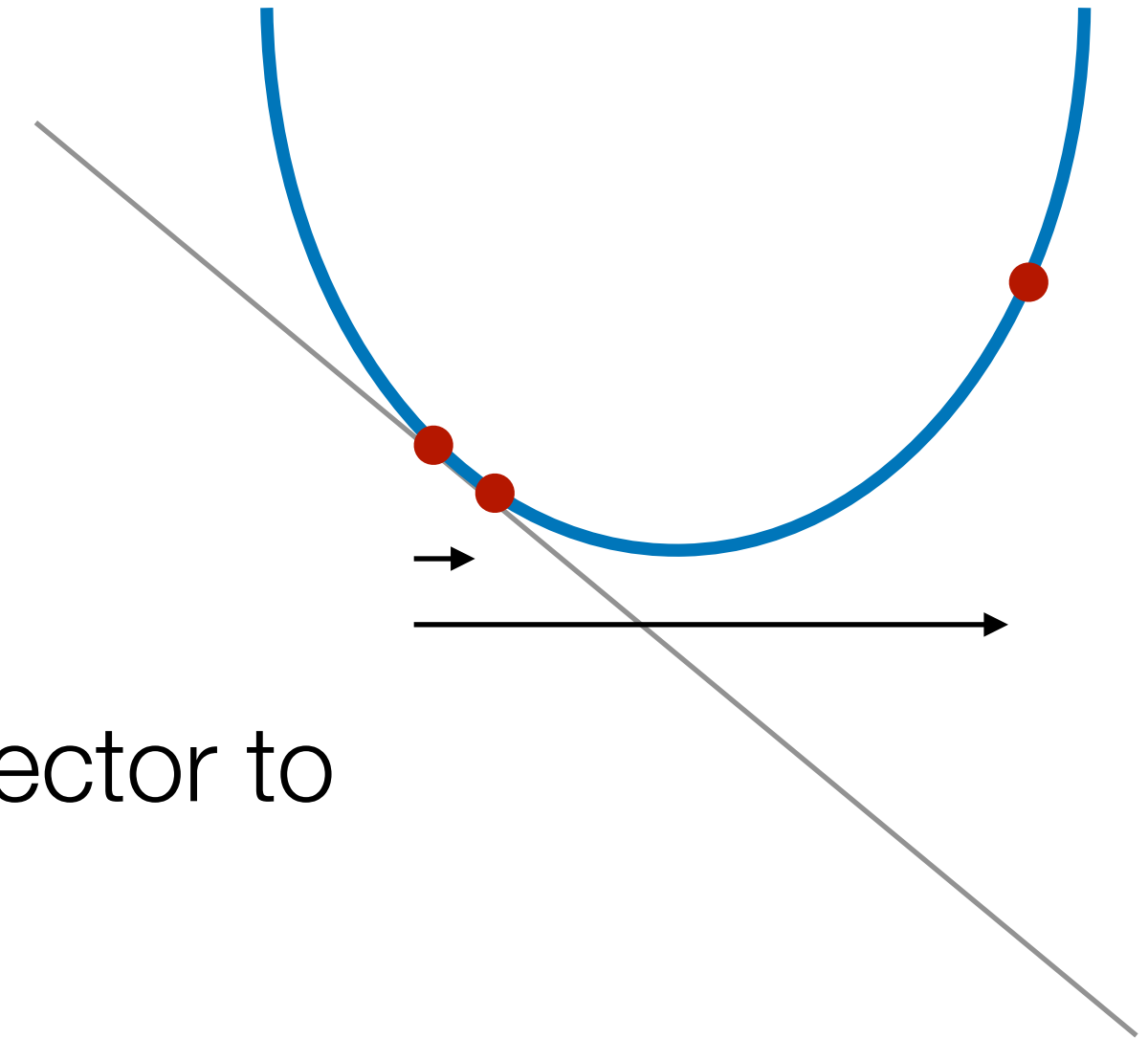
$$\frac{\partial}{\partial x_i} f(\mathbf{x}) = \frac{d}{dx_i} g(x_i).$$

Gradient

- The **gradient** of a function $f(\mathbf{x})$ is just a **vector** that contains all of its **partial derivatives**:

$$\nabla f(\mathbf{x}) = \begin{bmatrix} \frac{\partial}{\partial x_1} f(\mathbf{x}) \\ \vdots \\ \frac{\partial}{\partial x_n} f(\mathbf{x}) \end{bmatrix}$$

Gradient Descent



- The gradient of a function tells how to change every element of a vector to **increase** the function
 - If the partial derivative of x_i is positive, increase x_i
- **Gradient descent:**
Iteratively choose new values of \mathbf{x} in the (opposite) direction of the gradient:

$$\mathbf{x}^{new} = \mathbf{x}^{old} - \eta \nabla f(\mathbf{x}^{old}) .$$

- This only works for **sufficiently small** changes (**why?**)

- **Question:** How much should we change \mathbf{x}^{old} ?

learning rate

Where Do Gradients Come From?

Question: How do we compute the gradients we need for gradient descent?

1. Analytic expressions / direct implementation:

$$\begin{aligned}L(\mu) &= \frac{1}{n} \sum_{i=1}^n (y(i) - \mu)^2 \\ &= \frac{1}{n} \sum_{i=1}^n [y(i)^2 - 2y(i)\mu + \mu^2] \\ \nabla L(\mu) &= \frac{1}{n} \sum_{i=1}^n [-2y(i) + 2\mu]\end{aligned}$$

Where Do Gradients Come From?

2. Method of differences

$$\nabla L(\mathbf{x})_i \approx L(\mathbf{x} + \epsilon \mathbf{e}_i) - L(\mathbf{x})$$

(for "sufficiently" tiny ϵ)

Question: Why would we ever do this?

Question: What are the drawbacks?

Where Do Gradients Come From?

3. The Chain Rule (of Calculus)

$$\frac{dz}{dx} = \frac{dz}{dy} \frac{dy}{dx}$$

$$\text{i.e., } h(x) = f(g(x)) \implies h'(x) = f'(g(x))g'(x)$$

- If we know formulas for the derivatives of **components** of a function, then we can build up the derivative of their composition mechanically
- Most prominent example: **Back-propagation** in neural networks

Approximating Real Numbers

- Computers store real numbers as **finite number** of bits
- **Problem:** There are an **infinite number** of real numbers in any interval
- Real numbers are encoded as **floating point numbers:**
 - $$\underbrace{1.001\dots011011}_{\text{significand}} \times 2^{\underbrace{1001\dots0011}_{\text{exponent}}}$$
 - *Single precision:* 24 bits **significand**, 8 bits **exponent**
 - *Double precision:* 53 bits significand, 11 bits exponent
- **Deep learning** typically uses single precision!

Underflow

$$\underbrace{1.001\dots011010}_{\text{significand}} \times 2^{\underbrace{1001\dots0011}_{\text{exponent}}}$$

- Numbers that are smaller than $1.00\dots01 \times 2^{-1111\dots1111}$ will be rounded down to **zero**
- Sometimes that's okay! (Almost every number gets rounded)
- Often it's not (**when?**)
 - Denominators: causes divide-by-zero
 - log: returns -inf
 - log(negative): returns nan

Overflow

$$\underbrace{1.001\dots011010}_{\text{significand}} \times 2^{\underbrace{1001\dots0011}_{\text{exponent}}}$$

- Numbers bigger than $1.111\dots1111 \times 2^{1111}$ will be rounded up to **infinity**
- Numbers smaller than $-1.111\dots1111 \times 2^{1111}$ will be rounded down to **negative infinity**
- **exp** is used very frequently
 - Underflows for very negative numbers
 - Overflows for "large" numbers
 - **89** counts as "large"

Addition/Subtraction $1.\underbrace{001\dots011010}_{\text{significand}} \times 2^{\underbrace{1001\dots0011}_{\text{exponent}}}$

- Adding a small number to a large number can have no effect (**why?**)

Example:

```
>>> A = np.array([0., 1e-8])
```

```
>>> A = np.array([0., 1e-8]).astype('float32')
```

```
>>> A.argmax()
```

```
1
```

```
>>> (A + 1).argmax()
```

```
0
```

```
>>> A+1
```

```
array([1., 1.], dtype=float32)
```

1e-8 is **not** the
smallest possible
float32

Softmax

$$\text{softmax}(\mathbf{x})_i = \frac{\exp(x_i)}{\sum_{j=1}^n \exp(x_j)}$$

- **Softmax** is a very common function
- Used to convert a vector of activations (i.e., numbers) into a **probability distribution**
 - **Question:** Why not normalize them directly without **exp**?
- But **exp overflows** very quickly:
 - Solution: $\text{softmax}(\mathbf{z})$ where $\mathbf{z} = \mathbf{x} - \max_j x_j$

Log

- Dataset likelihoods shrink **exponentially** quickly in the **number of datapoints**

- **Example:**

- Likelihood of a sequence of 5 fair coin tosses = $2^{-5} = 1/32$

- Likelihood of a sequence of 100 fair coin tosses = 2^{-100}

- **Solution:** Use log-probabilities instead of probabilities

$$\log(p_1 p_2 p_3 \dots p_n) = \log p_1 + \dots + \log p_n$$

- log-prob of 1000 fair coin tosses is $1000 \log 0.5 \approx -693$

General Solution

- **Question:**
What is the most general solution to numerical problems?
- ***Standard libraries***
 - Theano, Tensorflow both **detect** common unstable expressions
 - scipy, numpy have stable implementations of many common patterns (e.g., softmax, logsumexp, sigmoid)

Summary

- **Gradients** are just vectors of **partial derivatives**
 - Gradients point "uphill"
- **Learning rate** controls how fast we walk uphill
- Deep learning is fraught with **numerical** issues:
 - Underflow, overflow, magnitude mismatches
 - Use **standard implementations** whenever possible